

Model WL50-HD-LPG Headed Industrial Transporter

Specifications



Dimensions

| Length | 15 feet / 4572 mm |
|----------------------|--------------------|
| Width | 6.5 feet / 1981 mm |
| Height – Lowered | 18.5 in / 470 mm |
| Height – Raised | 24.5 in / 622 mm |
| Load Deck Dimensions | |
| Length | 12 feet / 3658 mm |
| Width | 6.5 feet / 1981 mm |
| Suspension | Hydraulic |
| | |

Weights

| Transporter Empty Weight | 12,000 lb / 5,455 kg |
|---------------------------|------------------------|
| Transporter Loaded Weight | 112,000 lb / 50,900 kg |
| Rated Capacity | 100,000 lb / 45,450 kg |

Engine

| Туре | LPG (Diesel Optional) |
|--------------|-----------------------|
| Displacement | 59 cu in / 1.0 L |
| Cylinders | 3 |
| Cooling | Liquid |

Drive System

| Number of Wheel Modules | 4 |
|-------------------------|------------------|
| Wheel Diameter | 12 in / 305 mm |
| Wheel Width | 6 in / 152 mm |
| Propulsion | AC Servo |
| Steering | Joystick Control |

Speeds

| Empty | 0 – 110 fpm / 33.5 mpm |
|-----------------|---------------------------|
| Loaded | 0 – 80 fpm / 24.4 mpm |
| Raise (maximum) | 6.0 in per min (152 mmpm) |
| Lower (maximum) | 6.0 in per min (152 mmpm) |

Environmental Conditions

| Maximum Operating Temperature | 110° F / 43° C |
|-------------------------------|----------------|
| Minimum Operating Temperature | 20° F / -7° C |
| Relative Humidity | 0 - 100% |
| Maximum Slope | 4% |

Omni-Directional Steering Modes

| Normal (All Wheel Steering) Travel forward and reverse parallel to the transporter's long axis. Front wheels steer ±30°. Rear wheels steer opposite direction of front. | Lateral (All Wheel Steering) Travel forward and reverse parallel to the transporter's short axis. Front wheels steer ±30°. Rear wheels steer opposite direction of front. | Normal Diagonal Travel forward and reverse at an angle to the transporter's short axis Front and rear wheels steer together. |
|--|--|---|
| travel | | Se Vou Se |
| Lateral Diagonal | Rotate | RotatePLUS |
| | Notate | |
| Travel forward and reverse at an angle to the transporter's long axis. Front and rear wheels steer together. | All modules align axle centerlines to theoretical center of transporter. Rotate clockwise or counter- clockwise about the center of the transporter. | All modules align axle centerlines to a point along the transporter's shor axis. Rotate clockwise or counter- clockwise about transporter's short axis. |

| Machine Controller | Beckhoff Industrial PC TwinCAT ladder logic running Doerfer's control software. |
|--------------------|--|
| Operator Interface | Wireless bellipak radio joystick control with Beckhoff color touch screen HMI (Human Machine Interface). |

Specifications subject to change without notice

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Authorized Wheelift Representative

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